

# A Model-Informed Deep Learning Algorithm for Solving Inverse Problems

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Joint work with Dinh-Liem Nguyen

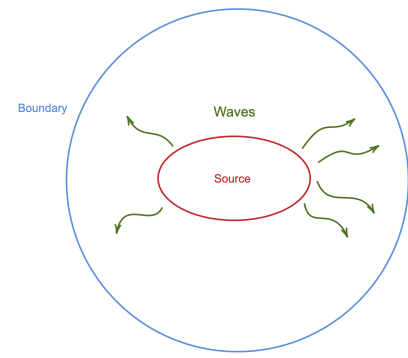
# Outline

- 1 Introduction
- 2 Stable Imaging Function
- 3 Numerical Results
- 4 Extension to Inverse Scattering Problems

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# Introduction



**Direct source problem:** Given a source that radiates waves, determine the waves.

**Applications:** Radar, non-destructive testing, geophysical exploration, medical imaging, ...

# Inverse source problem

- Let  $f \in L^2(\Omega)$ , where  $\Omega$  is a large disk such that  $\text{supp}(f) = D \subset \Omega$ .

$$\begin{cases} \Delta u + k^2 u = f, & \text{in } \mathbb{R}^2 \\ \frac{\partial u}{\partial r} - ik u = \mathcal{O}\left(\frac{1}{r^2}\right), & \text{as } r = |x| \rightarrow \infty. \end{cases}$$

- Inverse problem: **Given**  $u(\cdot, k)|_{\partial\Omega}$  for  $k \in [k_1, k_2]$ , **determine**  $f$ .

## Uniqueness and stability of solution for the inverse source problem:

- Bao, G., Lin, J., & Triki, F. (2010). A multi-frequency inverse source problem. *Journal of Differential Equations*, 249, 3443-3465.

### Theorem 1

*Given a set of real numbers  $[k_1, k_2]$ , the measurements  $u(\cdot, k)|_{\partial\Omega}$ , where  $k \in [k_1, k_2]$ , determine uniquely the source function  $f$ .*

## Traditional numerical schemes (far-from-complete list):

- *Bao, G., Lin, J., & Triki, F. (2011). Numerical solution of the inverse source problem for the Helmholtz Equation with multiple frequency data.*
- *Acosta, S., Chow, S., Taylor, J., & Villamizar, V. (2012). On the multi-frequency inverse source problem in heterogeneous media. Inverse Problems, 28.*
- *Eller, M., & Valdivia, N. (2009). Acoustic source identification using multiple frequency information. Inverse Problems, 25, 115005.*
- *Bao, G., Lin, J., & Triki, F. (2010). A multi-frequency inverse source problem. Journal of Differential Equations, 249, 3443-3465.*
- *Kress, R., & Rundell, W. (2013). Reconstruction of extended sources for the Helmholtz equation. Inverse Problems, 29.*
- *Karamehmedovi'c, M., Kirkeby, A., & Knudsen, K. (2018). Stable source reconstruction from a finite number of measurements in the multi-frequency inverse source problem. Inverse Problems, 34.*
- *Eibert, T.F. (2023). Multiple-Frequency Preconditioned Iterative Inverse Source Solutions. IEEE Transactions on Microwave Theory and Techniques, 71, 2842-2853.*

**Severely illposed**  $\implies$  numerical schemes require regularization strategies

## Deep learning-based algorithms (far-from-complete list):

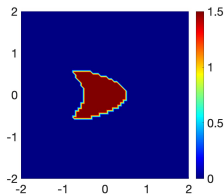
- Dong, Y., Sadiq, K., Scherzer, O., & Schotland, J.C. (2024). *Computational inverse scattering with internal sources: a reproducing kernel Hilbert space approach*. *Physical review. E*, 110 6-2, 065302 .
- Meng, S., & Zhang, B. (2024). *A Kernel Machine Learning for Inverse Source and Scattering Problems*. *SIAM J. Numer. Anal.*, 62, 1443-1464.
- Zhang, H., & Liu, J. (2023). *Solving an inverse source problem by deep neural network method with convergence and error analysis*. *Inverse Problems*, 39.

Solve **inverse source problems** with **“internal” data**!

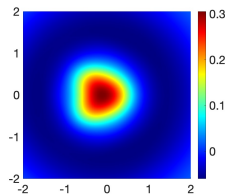
# Proposed Algorithm

We developed a 2-step **unsupervised** deep learning algorithm to solve the inverse source problem:

- Step 1: Convert the boundary data into an imaging function  $\mathcal{I}(z)$  which encodes geometrical information about  $f$ .
- Step 2: Use  $\mathcal{I}(z)$  as input for training. A model equation for  $\mathcal{I}(z)$  and  $f$  is employed to train a neural network which predicts  $f$ .



(a) Original source



(b) Data from  $\mathcal{I}$



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# Stable Imaging Function

- For each  $k \in [k_1, k_2]$ , for  $z \in \mathbb{R}^2$ , define the function

$$\mathcal{I}(z, k) := \int_{\partial\Omega} u(x, k) \overline{\Phi_k(x, z)} dS(x),$$

where  $\Phi_k(x, z)$  denotes the Green's function.

We assume the noisy data  $u_\delta$  satisfies

$$\|u - u_\delta\|_{L^2(\partial\Omega \times \mathbb{S})} \leq \delta \|u\|_{L^2(\partial\Omega \times \mathbb{S})}.$$

## Theorem 2

Let  $\mathcal{I}_\delta(z)$  the imaging function with noisy data  $u_\delta$ . Then

$$|\mathcal{I}(z) - \mathcal{I}_\delta(z)| \leq C\delta, \quad \text{for all } z \in \mathbb{R}^2,$$

where  $C$  is a positive constant which is independent of  $z$  and  $\delta$ .

# Significance of the model equation

## Theorem 3

*The imaging function  $\mathcal{I}(z)$  satisfies*

$$\mathcal{I}(z, k) = \frac{1}{4k} \int_{\Omega} J_0(k|y - z|) \textcolor{red}{f}(y) dy$$

Proof: Using the volume potential and the Helmholtz-Kirchhoff identity.

### Significance:

- A simple and nice connection between  $\mathcal{I}(z)$  and  $\textcolor{red}{f}$ .
- This equation will be used as a model equation in training our neural network with data  $\mathcal{I}(z)$ .

# Model Informed Neural Network

## Key Ideas:

- $\mathcal{I}(z)$  can be obtained robustly and inexpensively from (noisy) scattering data.
- Use input data  $\mathcal{I}(z)$  and the model equation to train neural network  $f_{\Theta}$  to predict  $f$ .

# Training Process

**Ansatz Space/Hypothesis space  $\mathcal{H}$**  : Space of Neural Networks with the following configuration:

- Depth of Neural Network: 4
- Width of Neural Network: 64
- Activation Functions: Hyperbolic Tangent Function

# Training Process

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With the chosen space  $\mathcal{H}$  in place, our physics-based loss functional  $\mathcal{L}[\cdot]$  is:

$$\mathcal{L} : \mathcal{H} \rightarrow \mathbb{R}$$

$$f_{\theta} \mapsto \frac{1}{M} \sum_{i=1}^M \left( \frac{1}{N} \sum_{j=1}^N \left[ \mathcal{I}(z_j, k_i) - \frac{1}{4k_i} \int_{\Omega} J_0(k_i |z_j - y|) f_{\theta}(y) dy \right] \right).$$

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Minimization Problem:

$$\min_{w_\theta \in \mathcal{H}} \frac{1}{M} \sum_{i=1}^M \left( \frac{1}{N} \sum_{j=1}^N \left[ \mathcal{I}(z_j, k_i) - \frac{1}{4k_i} \int_{\Omega} J_0(k_i |z_j - y|) w_\theta(y) dy \right] \right)$$

# Visual Representation

Let  $z = (x, y)^T \in \mathbb{R}^2$ .

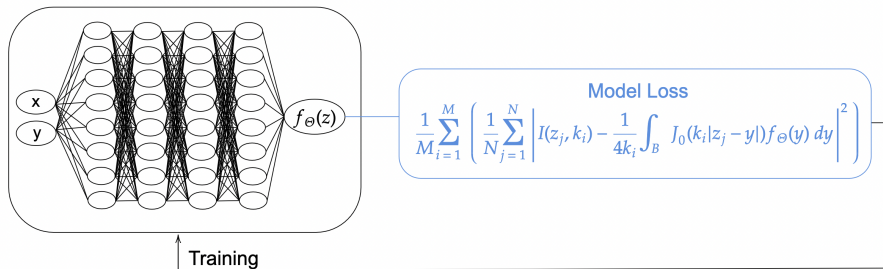


Figure 2: Visual representation of the model-informed neural network

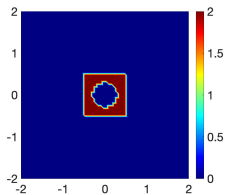


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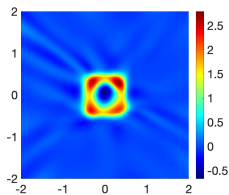
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# Numerical results

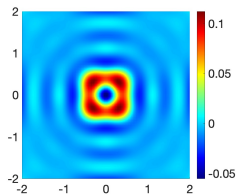
Reconstruction with 20% artificial noise introduced to the boundary data:



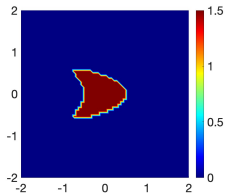
(a) Original Source



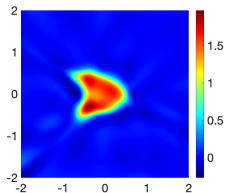
(b) Predicted



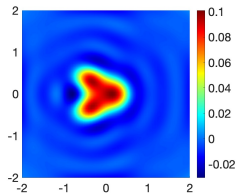
(c) Least Square



(a) Original Source



(b) Predicted



(c) Least Square

We have developed an unsupervised, model-informed deep learning algorithm to solve inverse source problems

- In step 1, regularization is done automatically  $\implies$  **no need** for additional regularization
- The algorithm incorporates a simple model integral equation into the deep learning process instead of PDE models, eliminating the need for automatic differentiation  $\implies$  **computationally cheaper**
- The method is **highly robust against noisy data**, ensuring stability and accuracy in practical applications.

# Outline

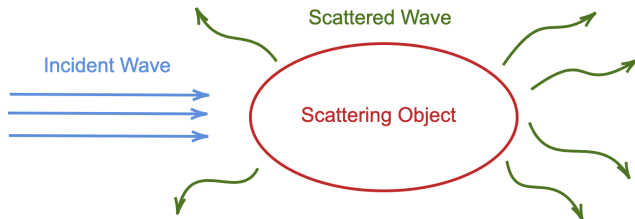
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# Extension - Inverse Scattering Problems

Can be extended to solve inverse scattering problems too

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**Inverse scattering problem:** Determine the *scattering object* from boundary measurements of **scattered wave** (for several **incident waves**).

**Applications:** Radar, non-destructive testing, geophysical exploration, medical imaging, ...

# Mathematical Formulation

- Let  $\eta : \mathbb{R}^2 \rightarrow \mathbb{R}$  be bounded function satisfying  $\eta = 0$  in  $\mathbb{R}^2 \setminus \overline{D}$ . Let  $\Omega$  be large disk such that  $D \subset \Omega$ . Consider incident waves

$$u^{in}(x, d) = e^{ikd \cdot x}$$

where  $d \in \mathbb{S}^1 := \{x \in \mathbb{R}^2 : |x| = 1\}$ .

- Consider the following model problem

$$\begin{cases} \Delta u + k^2(1 + \eta(x))u = 0, & \text{in } \mathbb{R}^2 \\ u = u^{in} + u^{sc}, \\ \lim_{r \rightarrow \infty} r^{\frac{n-1}{2}} \left( \frac{\partial u^{sc}}{\partial r} - ik u^{sc} \right) = 0, & r = |x|. \end{cases}$$

- Inverse Problem:** Given  $u^{sc}(\cdot, d)|_{\partial\Omega}$  for all  $d \in \mathbb{S}^1$ , determine  $\eta$ .

# Deep Learning for inverse scattering

## Supervised learning-based algorithms (far-from-complete list)

- Wei, Z., & Chen, X. (2019). *Deep-Learning Schemes for Full-Wave Nonlinear Inverse Scattering Problems*. *IEEE Transactions on Geoscience and Remote Sensing*, 57, 1849-1860.
- Khoo, Y., & Ying, L. (2018). *SwitchNet: a neural network model for forward and inverse scattering problems*. *ArXiv*, abs/1810.09675.
- Sanghvi, Y., Kalepu, Y., & Khankhoje, U.K. (2020). *Embedding Deep Learning in Inverse Scattering Problems*. *IEEE Transactions on Computational Imaging*, 6, 46-56.
- Chen, X., Wei, Z., Li, M., & Rocca, P. (2020). *A Review of Deep Learning Approaches for Inverse Scattering Problems (Invited Review)*. *Progress In Electromagnetics Research*.
- Gao, Y., Liu, H., Wang, X., & Zhang, K. (2021). *On an artificial neural network for inverse scattering problems*. *J. Comput. Phys.*, 448, 110771.
- Zhou, M., Han, J., Rachh, M., Borges, C. (2022). *A Neural Network Warm-Start Approach for the Inverse Acoustic Obstacle Scattering Problem*. *ArXiv*, abs/2212.08736.
- ...

Reconstruct unknown scattering objects that are **similar or closely related** to known training datasets!



## Unsupervised learning: Physics Informed Neural Networks (PINNs)

- Raissi, M., Perdikaris, P., & Karniadakis, G.E. (2019). *Physics-informed neural networks: A deep learning framework for solving forward and inverse problems involving nonlinear partial differential equations*. *J. Comput. Phys.*, 378, 686-707.
- Chen, Y., Lu, L., Karniadakis, G.E., & Dal Negro, L. (2019). *Physics-informed neural networks for inverse problems in nano-optics and metamaterials*. *Optics express*, 28 8, 11618-11633 .
- Chen, Y., & Dal Negro, L. (2021). *Physics-informed neural networks for imaging and parameter retrieval of photonic nanostructures from near-field data*. *APL Photonics*.
- Pokkunuru, A., Rooshenas, P., Strauss, T., Abhishek, A., & Khan, T.R. (2023). *Improved Training of Physics-Informed Neural Networks Using Energy-Based Priors: a Study on Electrical Impedance Tomography*. *International Conference on Learning Representations*.

Study **inverse design problems with “internal” data!**

# Imaging Function

- For  $z \in \mathbb{R}^2$ , define the function

$$\mathcal{I}(z) := \int_S \int_{\partial\Omega} u^{sc}(x, d) \overline{\Phi(x, z)} ds(x) \Phi^\infty(d, z) ds(d),$$

where  $\Phi(x, z)$  and  $\Phi^\infty(d, z)$  denote the Green's function and its scattering amplitude respectively.

With the Helmholtz-Kirchhoff Identity, Funk-Hecke Formula and Born approximation, we can derive

$$\mathcal{I}(z) - \frac{k\pi}{2} \int_D J_0^2(k|y - z|) \eta(y) dy = 0.$$

- A simple and nice connection between  $\mathcal{I}(z)$  and  $\eta$ .
- This equation will be used as a (simplified) model equation in training our neural network with data  $\mathcal{I}(z)$ .

# Stable Imaging Function

We assume the noisy data  $u_\delta^{sc}$  satisfies

$$\|u^{sc} - u_\delta^{sc}\|_{L^2(\partial\Omega \times \mathbb{S})} \leq \delta \|u^{sc}\|_{L^2(\partial\Omega \times \mathbb{S})}.$$

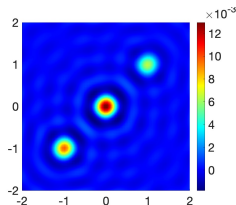
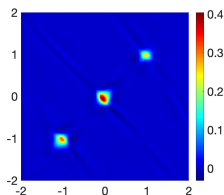
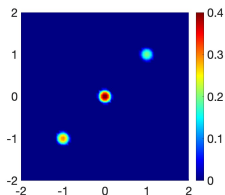
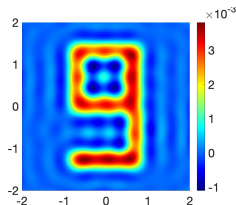
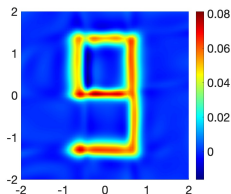
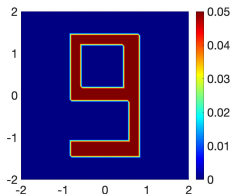
## Theorem 4

Let  $I_\delta(z)$  the imaging function with noisy data  $u_\delta^{sc}$ . Then

$$|\mathcal{I}(z) - \mathcal{I}_\delta(z)| \leq C\delta, \quad \text{for all } z \in \mathbb{R}^2,$$

where  $C$  is a positive constant which is independent of  $z$  and  $\delta$ .

# Some numerical results



(a) Original Scatterer

(b) Predicted

(c) Least Square

We have developed an unsupervised, model-informed deep learning algorithm to solve inverse scattering problems

- Unsupervised  $\implies$  **greater generalisability**
- Similar to the case of the algorithm for the inverse source problem, the algorithm is **computationally cheap**
- Again, the method is **highly robust against noisy data**, ensuring stability and accuracy in practical applications.

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Thank you for listening!